# Inexact Graph Matching: A Case of Study 

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#### Abstract

Inexact graph matching has become an important research area because it is used to find similarities among objects in several real domains such as chemical and biological compounds. Let $G$ and $G^{\prime}$ be input labeled graphs, we present an algorithm capable to find a graph $S$ of $G$, where $S$ is isomorphic to $G^{\prime}$ and the corresponding labels between the vertices and edges of $S$ and $G^{\prime}$ are not the same (inexact matching). We use a listcode based representation without candidate generation, where a step by step expansion is implemented. The proposed approach is suitable to work with directed and undirected graphs. We conducted a set of experiments in a genome database in order to show the effectiveness of our algorithm. Our experiments show a promissing method to be used with scalable graph matching tools that can be applied to areas such as Machine Learning (ML) and Data Mining (DM).


## Introduction

Graphs are a powerful and flexible knowledge representation used to model simple and complex structured domains (Cook \& Holder 1994). The representation power and flexibility is the main advantage of why the graph-based representation model has been adopted by researchers in different areas such as ML and DM (Cook \& Holder 1994; Kuramochi \& Karypis 2002). An important problem in ML and DM is to find similarities between objects. If we use a graph-based representation, the problem turns into finding similarities between graphs, which includes tasks as exact and inexact matching, where the graph / subgraph isomorphism detection is a critical operation (Cook \& Holder 1994). The task is not easy, because the subgraph isomorphism problem is known to be in NP-complete (Michael \& David 2003) then, in the worst case, the time to solve the decision problem is exponential, unless $\mathrm{P}=\mathrm{NP}$.

The exact matching (two graphs are similar if its topology and labeling is identical) is a widespread studied problem, where several works have been developed, each of them with different objectives. For example, Subdue (Cook \& Holder 1994) is an algorithm that implements a computationallyconstrained beam search, however the algorithm may not al-

[^0]ways find an isomorphism when it does exist (but it is capable to work the inexact problem). Some algorithms reduce the computational complexity by imposing topological restrictions on the input graphs (Luks 1982). There are other subgraph isomorphism projects such as Ullman (Ullman 1976), VF2 (Cordella et al. 2001) and Nauty (Brendan 1981) that are not able to work with labeled graphs, because many of them are oriented only to solve mathematical problems, and do not consider other classes of problems where labels represent important information. There are other works that explore ideas where the completeness is not sacrificed. AGM (Inokuchi \& Washio 2003), FSG (Kuramochi \& Karypis 2002), gSpan (Xifeng \& Han 2002) and SI-COBRA (Olmos, Gonzalez, \& Osorio 2005) are some algorithms that make use of strategies and representations with the aims to reduce the number of operations to perform and then being more efficient.

On the other hand, inexact graph matching is an important graph-theoretical problem, because it is used to find inexact similarities between objects. The inexact matching task consists on finding a distortion or variation between two input graphs, where there may not exist an exact match (Cook \& Holder 1994; Hlaoui \& Wang 2002; Cordella et al. 1996). Throughout this work, we consider an inexact match between two graphs in the sense that they have an identical topology (there exists a bijection between the vertices and edges of the graphs), nevertheless the labels of the vertices and edges might not be the same.

In this work, we present an algorithm capable of finding a graph $S$ of $G$, where $S$ is isomorphic to $G^{\prime}$ and the corresponding labels between the vertices and edges of $S$ and $G^{\prime}$ are not the same (inexact matching). We use a list-code based representation without candidate generation, where a step by step expansion with an exploration in depth is implemented. The proposed approach is suitable to work with directed and undirected graphs. We conducted a set of experiments in genome databases in collaboration with biology experts in order to study the effectiveness of our method (our method has already been applied to other theoretical and practical domains). Our experimental results show a promissing method to be used with scalable graph matching tools that can be applied to research areas such as Machine Learning (ML) and Data Mining (DM).

## The Subgraph Isomorphism Problem

As mentioned before, graphs have been used in several research areas. Different authors define a graph with some variations, according to their requirements. In this work, we assume that a graph is a 6-tuple $G=\left(V, E, L_{V}, L_{E}, \alpha, \beta\right)$, where:

- $V=\left\{v_{i} \mid i=1, \ldots, n\right\}$, is the finite set of vertices, $V \neq \emptyset$
- $E \subseteq V x V$, is the finite set of edges, $E=\{e=$ $\left.\left\{v_{i}, v_{j}\right\} \mid v_{i}, v_{j} \in V\right\}$
- $L_{V}$, is a set of vertex labels
- $L_{E}$, is a set of edge labels
- $\alpha: V \rightarrow L_{V}$, is a function assigning labels to the vertices
- $\beta: E \rightarrow L_{E}$, is a function assigning labels to the edges

Let $G$ be a graph, where $G=\left(V, E, L_{V}, L_{E}, \alpha, \beta\right)$. A subgraph $S$ of $G$, denoted by $S \subseteq G, S=$ $\left\{V^{S}, E^{S}, L_{V}^{S}, L_{E}^{S}, \alpha^{S}, \beta^{S}\right\}$ is a graph such that $V^{S} \subseteq V$, $E^{S} \subseteq E, \alpha^{S} \subseteq \alpha$ and $\beta^{S} \subseteq \beta$.
Given two graphs $G^{\prime}=\left(V^{\prime}, E^{\prime}, L_{V}^{\prime}, L_{E}^{\prime}, \alpha^{\prime}, \beta^{\prime}\right)$ and $G=\left(V, E, L_{V}, L_{E}, \alpha, \beta\right), G^{\prime}$ is isomorphic to $G$, denoted as $G^{\prime} \cong G$, if there exist $f: V^{\prime} \rightarrow V$ and $g: E^{\prime} \rightarrow E$ as bijections, where:

- $\forall v^{\prime} \in V^{\prime}, \alpha^{\prime}\left(v^{\prime}\right)=\alpha\left(f\left(v^{\prime}\right)\right)$
- $\forall\left\{v_{i}^{\prime}, v_{j}^{\prime}\right\} \in E^{\prime}, \beta^{\prime}\left(\left\{v_{i}^{\prime}, v_{j}^{\prime}\right\}\right)=\beta\left(g\left(\left\{v_{i}^{\prime}, v_{j}^{\prime}\right\}\right)\right)$

This definition only applies for exact matching. For inexact graph matching, bijection functions of $G^{\prime}$ are defined in a different way. Let $G^{\prime}=\left(V^{\prime}, E^{\prime}, L_{V}^{\prime}, L_{E}^{\prime}, \alpha^{\prime}, \beta^{\prime}\right)$ be a graph, where $V^{\prime}, E^{\prime}, L_{V}^{\prime}$ and $L_{E}^{\prime}$ are defined as we previously described. On the other hand:

- $\alpha^{\prime}: V^{\prime} \rightarrow 2^{L_{V}^{\prime}}$, power set of $L_{V}^{\prime}$, where $\forall v_{i}^{\prime}, v_{j}^{\prime} \in V^{\prime}$ : $\alpha^{\prime}\left(v_{i}\right) \cap \alpha^{\prime}\left(v_{j}\right)=\varnothing$ if $\alpha^{\prime}\left(v_{i}\right) \neq \alpha^{\prime}\left(v_{j}\right)$
- $\beta^{\prime}: E^{\prime} \rightarrow 2^{L_{E}^{\prime}}$, power set of $L_{E}^{\prime}$, where $\forall e_{i}^{\prime}, e_{j}^{\prime} \in E^{\prime}$ : $\alpha^{\prime}\left(e_{i}\right) \cap \alpha^{\prime}\left(e_{j}\right)=\varnothing$ if $\alpha^{\prime}\left(e_{i}\right) \neq \alpha^{\prime}\left(e_{j}\right)$
Considering the above mentioned, $G^{\prime}$ is inexact isomorphic to $G$, denoted as $G^{\prime} \cong_{I} G$, if there exist $f_{I}: V^{\prime} \rightarrow V$ and $g_{I}: E^{\prime} \rightarrow E$ as bijections, where:
- $\forall v^{\prime} \in V^{\prime}, f_{I}\left(v^{\prime}\right)=v: \alpha(v) \in \alpha^{\prime}\left(v^{\prime}\right)$
- $\forall e^{\prime} \in E^{\prime}, g_{I}\left(e^{\prime}\right)=e: \beta(e) \in \beta^{\prime}\left(e^{\prime}\right)$

Based on these concepts, we say that $G^{\prime}$ is a subgraph isomorphic of $G$ if there exists $S \subseteq G$ such that $G^{\prime} \cong S$ for exact matching, or $G^{\prime} \cong_{I} S$ for inexact matching.

In other words, an isomorphism between $G^{\prime}$ and $G$ exists if the topology of both graphs is exactly the same and the labeling is identical for exact match. Note that if $\left|L_{V}^{\prime}\right|=$ $\left|L_{E}^{\prime}\right|=1$, then we have the traditional SI problem. It is clear that we are working an NP - complete problem, where some instances can fall in the worst case, but not all of them.

## The IGM-COBRA Algorithm

In a previous work (Olmos, Gonzalez, \& Osorio 2005), we developed an algorithm to detect the exact instances of a graph $G^{\prime}$ in a graph $G$ (called Subgraph Isomorphism - COde Based Representation Algorithm, or SI-COBRA),


Figure 1: Finding a Subgraph Isomorphism Based on Lists of Codes
where a linear sequence of codes is used to represent the graphs. A code, denoted by $c_{i}$, represents the information of an edge label $e$ and its adjacent vertices (a code based representation has also been successfully applied in gSpan (Xifeng \& Han 2002)). Each code $c_{i}$ is sorted in a linear sequence called $L_{V E V}=\left\{c_{i}: i=1, \ldots, s\right\}$, where $s$ is the number of different combinations of labels. A new lexicographic order is implemented using criteria such as vertices degrees, statistical summaries of the codes and an order based on the labels.

Our method starts by building a graph model of $G^{\prime}$, represented by a linear sequence of codes, called $D F C^{\prime}$. The $D F C^{\prime}$ model is a sorted sequence of codes $<$ $d f c_{1}^{\prime}, \ldots, d f c_{n}^{\prime}>$, where each entry $d f c_{x}^{\prime}=\left(i, j, c_{k}, t\right)$ and $i, j$ are the indexes associated to the adjacent vertices of edge $e_{x} \in E^{\prime}, c_{k}$ is a code that represents the label's information of the edge $e_{x}, c_{k}=L_{V E V}\left(e_{x}\right)$ and $t$ is a special mark to classify the edges as $F$ (forward) or $B$ (backward) edges (Olmos, Gonzalez, \& Osorio 2005).

We use three basic criteria to sort the $D F C^{\prime}$ sequence: a) the degree of the vertices; b) the label that has the largest number of instances and c) the combination of the labels (lexicographic order based on $L_{V E V}$ ). With these restrictions and using a $D F S$ strategy, the $D F C^{\prime}$ code is built as follows:

1. Select a non visited vertex $v_{i}$ in $G^{\prime}\left(v_{i}\right.$ satisfying restrictions a), b) and c)
2. Expand vertex $v_{i}$ to vertex $v_{j},\left(v_{j}\right.$ has not been visited yet and satisfies restrictions a), b) and c)
3. Add $\left(i, j, L_{V E V}\left(\left\{v_{i}, v_{j}\right\}\right), F\right)$ to $D F C^{\prime}$ (a forward edge)
4. Expand all possible backward edges: $\forall\left\{v_{j}, v_{x}\right\}$ where $v_{x}$ has already been visited, add $\left(j, x, L_{V E V}\left(\left\{v_{j}, v_{x}\right\}\right), B\right)$ to $D F C^{\prime}$ according to the $L_{V E V}$ order
5. If $v_{j}$ has an adjacent vertex $v_{x}$ that has not been visited yet, go to step 2 with $v_{j}$ as $v_{i}$ and $v_{x}$ as $v_{j}$
6. If there are vertices that have not been visited yet, go to step 1. In other case, finish
Based on $D F C^{\prime}$ (the model of $G^{\prime}$ ), the matching process tries to build a linear sequence $D F C$ of $G$. The size of $D F C$ must be the same of $D F C^{\prime}$ and the corresponding codes entries must also be identical. If $D F C$ could be generated, then we found $S \subseteq G$, where $S$ is represented by $D F C$ and $G^{\prime} \cong S$. This idea is shown in Fig. 1.

In the matching proces, $D F C$ is built with a step by step expansion without candidate's generation. First, we ap-


Figure 2: Example of a Width-Depth Search using $L_{V E V}$ Codes
ply a pruning phase in $G$ that aims to reduce the number of operations to perform, where $\forall v \in V: \alpha(v) \notin L_{V}^{\prime}$ and $\forall e \in E: \beta(e) \notin L_{E}$ are removed. This task can be performed with the use of $L_{V E V}$, removing $\forall e \in G$ : $L_{V E V}(e) \notin L_{V E V}$. Moreover, with a statistical analysis based on $L_{V E V}$, we can remove edges in $G$ without the minimum number of repetitions. We also use the vertices degrees and their number of repetitions in the graph to further prune $G$. Without loosing generality, consider that $d e g_{\text {min }}\left(\alpha_{1}\right), \ldots, \operatorname{deg}_{\min }\left(\alpha_{n}\right)$ are the minimum degrees associated to each label $\alpha_{x} \in L_{V}^{\prime}$. Then, $\forall v \in V$ can not be common if $\operatorname{deg}(\alpha(v))<\operatorname{deg}_{\min }\left(\alpha^{\prime}\right)$ and $\alpha(v)=\alpha^{\prime}(F S G$ uses a similar concept to order the vertices in an adjacency matrix). Note that after this preprocessing phase, $G$ might have been partitioned in $s$ connected graphs. Each of those graphs will be compared with $G^{\prime}$. Let GSet be the set of graphs derived from this process.

Next, the processing phase consists on finding the mapping between vertices and edges of $G^{\prime}$ and $G_{i}$, where $G_{i} \in$ GSet (the process is applied to each graph in GSet, while a $D F C$ code has not been found). We implement a backtracking algorithm, because this technique is fairly stable and performs well in most cases, since it does not require more resources than those strictly necessary and a new partial result is based on a previous result. Since $D F C^{\prime}$ is an array, the backtracking strategy can be used.

The process starts by finding the vertices $v \in G_{i}$ where $\alpha(v)=\alpha\left(v_{i}\right), v_{i} \in G^{\prime}, \operatorname{deg}(v) \geq \operatorname{deg}\left(v_{i}\right)$, and $d f c_{1}^{\prime}=$ $\left(i, j, c_{x}, F\right)$ where $c_{x}=L_{V E V}\left(\left\{v_{i}, v_{j}\right\}\right)$ (each vertex forms a root of expansion). Taking these vertices, the construction process of $D F C$ begins, where the algorithm finds all the possible mappings that can be associated to entry $d f c_{i}^{\prime}$ of $D F C^{\prime}$, that is, each edge where the code $c_{x}$ is the same. This process is performed with a step by step expansion without candidate generation, where the $L_{V E V}$ values are used to compare the mappings. Moreover, for each expansion step where there does not exist the minimun number of $L_{V E V}$ combinations we pruned that expansion path and we avoid exploring these combinations.

Fig. 2 shows an example based on the $L_{V E V}$ codes and a width-depth search strategy. In this example, we can see how the partial result vectors are generated and pruned. It is also possible to find all the instances of a graph $G^{\prime}$ in a graph $G$, just by leaving the algorithm run over all the possibilities. In this example, there are two mappings.

However, the before mentioned concepts are oriented to find exact associations between graphs, because for each $d f c_{x}^{\prime} \in D F C^{\prime}$ and $d f c_{x} \in D F C, c_{x}^{\prime}=c_{x}$. With the aims to identify graphs with an identical topology but where the vertices and edges labels may vary (inexact matching), we propose the IGM-COBRA (Inexact Graph Matching) algorithm based on the following:

1. A new label $l_{x}$ is associated to each $\alpha^{\prime}\left(v_{i}\right)$ where $\left|\alpha^{\prime}\left(v_{i}\right)\right|>1$ (if two or more vertices in $G^{\prime}$ have the same $\alpha^{\prime}\left(v_{i}\right)$, then they will have the same label $l_{x}$ ). This sustitution process will also be applied to edge labels.
2. $L_{V E V}$ codes are built based on $G^{\prime}$ labels (considering the new $l_{x}$ labels).
3. The $D F C^{\prime}$ sequence is built following the rules described in the SI-COBRA algorithm description.
4. The prunning phase of $G$ is now modified. Vertices and edges are removed only considering the degree of the vertices. We are not using the $L_{V E V}$ codes for prunning because there might exist codes of $G$ that are not in $L_{V E V}$ but, may produce a valid association.
5. $G$ is explored in a similar way as in the SI-COBRA algorithm, with a step by step expansion in depth without candidate generation. However, there exists a variaton: we perform the degree test without considering the $L_{V E V}$ codes.
6. Each $d f c_{x}^{\prime}$ entry is processed in two phases: if $d f c_{x}^{\prime}$ contains a $l_{x}$ label, then it is necessary to consider each possible label that can produce a valid mapping. On the other hand, the comparison process is based on $L_{V E V}$ codes.
Clearly, the IGM-COBRA algorithm can not prune a high number of path expansions as SI-COBRA does. However, this is a consecuence of the inexact maching process, where a label in $G^{\prime}$ can take different values. For example, let $d f c_{x}^{\prime}$ be a code, where $d f c_{x}^{\prime}=\left(i, j, c_{k}, t\right), c_{k}=\left(a, l_{s}, b\right)$ and $l_{s}=\{c, d\}$. Consider that there exist two edges in $G$, where their codes are $c_{m}=(a, c, b)$ and $c_{n}=(a, d, b)$. Clearly, $c_{m}$ and $c_{n}$ are not equal to $c_{k}$. Nevertheless, $c_{m}$ and $c_{n}$ can be associated to $c_{k}$, because the last one produces two label combinations that are identical to the $c_{m}$ and $c_{n}$ codes. For this reason, if we are processing an entry with a label $l_{x}$ then we need to test each possible combination to detect valid mappings.

## Experimental Results

We conducted an experimental investigation in order to find low-complexity DNA sequences using the IGM-COBRA algorithm. For our experiments, we worked with the Aspergillus nidulans, Neurospora crassa and Ustilago maydis DNA databases, where each database is a sequence that consists of the four nitrogen-compound bases $a$ (adenine), $c$ (cytosine), $g$ (guanine) and $t$ (thymine). These databases are

| Organism | Database | Dimension <br> (MBytes) | \#Scaffolds |
| :---: | :--- | :---: | :---: |
| Aspergillus <br> nidulans | http://www.broad.itm.edu/cig- <br> bin/annotation/fungi/aspergillus/download_lic <br> ence.cgi/aspergillus_nidulans_1.fasta.gz | 30.5 | 248 |
| Neurospora <br> crassa | http://www.broad.mit.edu/cgi- <br> bin/annotation/fungi/neurospora/download_lic <br> ence.cgi/neurospora_3.fasta.gz | 39.8 | 251 |
| Ustillago <br> maydis | http://www.broad.mit.edu/cgi- <br> bin/annotation/fungi/ustilago_maydis/downlo <br> ad_license.cgi/ustilago_maydis_1.fasta.gz | 19.9 | 341 |

Figure 3: DNA Description Databases

Figure 4: Example of a DNA Sequence using a Graph-based Representation
divided in sections, called scaffolds. These DNA databases are free available through the Center for Genome Research (see figure 3) .

We represent a DNA sequence as follows. Given the DNA ordered sequence $\rho=<\sigma_{1}, \ldots, \sigma_{n}>, \sigma_{x} \in\{a, c, g, t\}$ ( $a$ denine, $c$ ytosine, $g$ uanine, $t$ hymine), then the graph-based representation for $\rho$ is the graph $G=\left(V, E, L_{V}, L_{E}, \alpha, \beta\right)$ where:

- $V=\left\{v_{x}: x=1, \ldots, n\right\}$ where $\exists$ a bijective function $\Phi: \rho \rightarrow V$
- $E=\left\{e_{x}: x=1, \ldots, n-1, e_{x}=\left(v_{i}, v_{i+1}\right) \forall e_{x}\right\}$
- $L_{V}=\{a, g, c, t\}$
- $L_{E}=\{n e x t\}$
- $\alpha: V \rightarrow L_{V}$
- $\beta: E \rightarrow L_{E}$

In our representation we map every base in the sequence to a vertex in the graph with the name of the base as the vertex label. In order to keep the sequence we add edges that connect vertices with the "next" label. For example, for the DNA sequence "cagctgcag" we create the graph shown in figure 4.

The low-complexity sequences $\rho^{\prime}=<\sigma_{1}^{\prime}, \ldots, \sigma_{n^{\prime}}^{\prime}>$ are represented with a graph $G^{\prime}=\left(V^{\prime}, E^{\prime}, L_{V}^{\prime}, L_{E}^{\prime}, \alpha^{\prime}, \beta^{\prime}\right)$ defined as follows:

- $V^{\prime}=\left\{v_{x}^{\prime}: x=1, \ldots, n^{\prime}\right\}$ where $\exists$ a biyective function $\Phi^{\prime}: \rho^{\prime} \rightarrow V^{\prime}$
- $E^{\prime}=\left\{e_{x}^{\prime}: x=1, \ldots, n^{\prime}-1, \forall e_{x}^{\prime}: e_{x}^{\prime}=\left(v_{i}^{\prime}, v_{i+1}^{\prime}\right)\right\}$
- $L_{V^{\prime}}^{\prime}=\{a, g, c, t, x\}$
- $L_{E^{\prime}}^{\prime}=\{n e x t\}$
- $\alpha^{\prime}: V^{\prime} \rightarrow L_{V^{\prime}}$
- $\beta^{\prime}: E^{\prime} \rightarrow L_{E^{\prime}}$


Figure 5: Runtime for the Aspergillus nidulans DNA Experiments


Figure 6: Runtime for the Neurospora crassa DNA Experiments

Note that $L_{V^{\prime}}^{\prime}$ includes a label $x$, where $x=\{a, t\}$. Then, the problem to find a low-complexity sequence in a DNA sequence using a graph-based representation is defined as follows: if $G^{\prime}$ represent the low-complexity sequence $\rho^{\prime}$ and $G$ the DNA sequence, then the problem to find $\rho^{\prime}$ in the DNA sequence is reduced to find a subgraph $S \subseteq G$ such that $G^{\prime} \cong_{I} S$.

For our experiments we transformed each database into its graph-based representation. After this, our domain experts suggested to look the $c x g_{m}$ sequence, where $x$ can be interchanged by any of the two bases ( $a$ or $t$ ) and $10 \leq m \leq 60$ (that is, $m$ represents the consecutive number of repetitions of the sequence, for example, $c x g_{3}=c x g c x g c x g$ ). In order to find the sequences in the genome, we ran the IGMCOBRA algorithm for each scaffold in its graph-based representation. Since we need to find each instance, we just leave the algorithm run over all the possibilities.

Figs. 5, 6 and 7 show the runtime execution performance of IGM-COBRA. These runtimes are divided in three sections: pre-processing time, which includes the reading input file and prunning phases; searching time, where $G$ is explored and total time, that includes the pre-processing time and the searching time.
Note that the running time increases according to the dimension of the DNA inputs and the behavior was consistent for all the databases (in other words, the running time was not exponential as it could be thought). Moreover, the pre-processing time is not expensive (considering that in this phase all codes are built). These are positive characteristics


Figure 7: Runtime for the Ustilago maydis DNA Experiments

|  | G |  | G after Pruned |  | \#Partitions | RunTime | Pruned Proportion |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | \#Vertices | \#Edges | \#Vertices | \#Edges |  |  | Vertices | Edges |
| Aspergillus | 2259 | 2258 | 418 | 263 | 155 | 0.016 | 81.50\% | 88.35\% |
|  | 10851 | 10850 | 1996 | 1337 | 659 | 0.14 | 81.61\% | 87.68\% |
|  | 168814 | 168813 | 24466 | 15615 | 8851 | 90.563 | 85.51\% | 90.75\% |
|  | 127977 | 127976 | 18991 | 11965 | 7026 | 50.672 | 85.16\% | 90.65\% |
|  | 155056 | 155055 | 22901 | 14368 | 8533 | 75.453 | 85.23\% | 90.73\% |
| Neurospora | 18603 | 18602 | 2402 | 1498 | 904 | 0.25 | 87.09\% | 91.95\% |
|  | 1842096 | 1842095 | 259549 | 163529 | 96020 | 10075.359 | 85.91\% | 91.12\% |
|  | 1776986 | 1776985 | 247684 | 154847 | 92837 | 9375.297 | 86.06\% | 91.29\% |
|  | 1337370 | 1337369 | 185798 | 116185 | 69613 | 5306.234 | 86.11\% | 91.31\% |
|  | 1198271 | 1198270 | 199494 | 131579 | 67915 | 5457.328 | 83.35\% | 89.02\% |
| Ustillago | 3049 | 3048 | 333 | 202 | 131 | 0.331 | 89.08\% | 93.37\% |
|  | 30180 | 30179 | 3819 | 2328 | 1491 | 0.906 | 87.35\% | 92.29\% |
|  | 510685 | 510684 | 58011 | 34757 | 23254 | 626.703 | 88.64\% | 93.19\% |
|  | 86435 | 86434 | 10124 | 6092 | 4032 | 16.234 | 88.29\% | 92.95\% |
|  | 82161 | 82160 | 9459 | 5696 | 3763 | 14.344 | 88.49\% | 93.07\% |

Figure 8: Results in three DNA Databases
of the IGM-COBRA algorithm showing a high performance.
Figure 8 shows five scaffold results (randomly selected) of each DNA database, where we can see the original $G$ graphs dimension ( $G$ columns) and their dimension after the pruning phase. We also illustrated the number of partitions induced by the algorithm (\#Partitions column), the runtime (RunTime column) and the vertices and edges proportion (percentage) pruned by the algorithm from G (Pruned Proportion column). It is interesting to note the high number of partitions induced by the algorithm. As a consequence, some of those graphs can be pruned (eliminating the whole graph) because they are smaller than the graph to search for. Another important consequence is the fact that the algorithm requires less computational resources to store and process the data, because only one partition is processed at a time, and this requires less memory than that used to process the original database. We can also see in the last two columns the effectiveness of the pruning phase because a high proportion of vertices and edges were eliminated.

The number of discovered sequences was variable. For example, we found 16464 sequences in the Ustillago maydis scaffold 1_29-2, (some of them are shown in Fig. 9). The dimension of the found sequences is also variable, for example, in Fig. 10 we show the dimension of some sequences according with its start possition (these sequences belong to Linkage Group 1, which is a classification defined in the domain).

According with our results, our algorithm was capable to finding sequences of different dimension in polynomial

| Dimension | Start Position | Position Sequence |
| :---: | :---: | :---: |
| 12 | 77142 | 77153 cagctgcagcag |
| 12 | 82646 | 82657 cagcagctgctg |
| 12 | 85520 | 85531 cagcagcagcag |
| 12 | 85544 | 85555 cagcagcagcag |
| 12 | 104554 | 104565 cagcagctgctg |
| 12 | 155329 | 155340 cagcagcagctg |
| 12 | 322568 | 322579 ctgctgctgctg |
| 15 | 105088 | 105102 ctgctgctgctgctg |
| 15 | 268708 | 268722 cagcagcagcagcag |
| 18 | 112404 | 112421 cagcagcagcagcagcag |
| 18 | 286708 | 286725 cagcagcagcagcagctg |
| 21 | 77668 | 77688 ctgctgctgctgctgctgctg |
| 21 | 121449 | 121469 ctgctgctgctgctgctgctg |
| 24 | 143567 | 143590 ctgctgctgctgctgctgctgctg |
| 39 | 139246 | 139284 ctgctgctgctgctgctgctgctgctgctgctgctgctg |
| 57 | 160502 | 160558 ctgctgctgctgctgctgctgctgctgctgctgctgctgctgctgctgctgctgctg |

Figure 9: Some Sequences Discovered in Ustillago maydis.


Figure 10: Example of Different Sequences Founded in Linkage Group 1 of Ustillago maydis.
time. Moreover, the response time was bounded by a quadratic polynomial with respect to the number of vertices.

## Conclusions and Future Work

In this work we presented an approach to solve the inexact subgraph isomorphism problem. We implement concepts like a list code based representation, a step by step expansion model without candidate generation and a prunning phase. In our experiments we use a DNA domain, with three different databases, with the aims to get a good measure of the proposed algorithm. Our experiments showed that our approach finds the mappings very quickly. Consequently, the global performance is attractive. We also tested the scalability of the algorithm, since the dimension of the databases is considerable. Currently, we are working with our domain experts to study how possible low-complexity sequences can be found with IGM-COBRA.

We will continue our research testing our approach with other algorithms focused to solve the inexact match problem and also, we will do experiments using graphs with different dimensions and topologies. Moreover, we are analysing new problems where it is possible to use the IGM-COBRA algorithm to find inexact instances.

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