Toward a Comprehensive Knowledge-Base for Engineering

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Abstract

Current knowledge-based systems are limited because they have little or underlying knowledge of the physics of the problem. In addition, the knowledge structures in these KBS do not provide an adequate foundation for systems than can perform innovative engineering problem solving. In this paper, we present a layered knowledge representation framework (KREEPS) that is being developed at the Intelligent Engineering Systems Laboratory. KREEPS is a part of our DICE effort, which involves the development of tools for collaborative engineering applications.

Introduction

Over the past six years we have been working on a computer-based architecture called DICE (Distributed and Integrated environment for Computer-aided Engineering) which is aimed at addressing coordination and communication problems in engineering. 1 Essentially, DICE can be envisioned as a network of agents or Knowledge Modules (KMs) which communicate through a shared workspace - the Blackboard. In DICE, an agent is viewed as a combination of a user and a computer. Agents (or KMs) in DICE are categorized into: Strategy, Specialist, Critic, and Quantitative KMs. The Strategy KMs help the Control Mechanism in the coordination and communication process. The Specialist KMs perform individual specialized tasks of the design and construction process. The Critic KMs check various aspects of the design process, while the Quantitative KMs are mostly algorithmic CAD tools. The Blackboard is divided into three Blackboards: Solution, Coordination, and Negotiation Blackboards.

The Specialist KMs encode engineering knowledge in various forms. To illustrate the types of knowledge used in the Specialist KMs, consider an example of a structural system, as shown in Figure 1. From the drawings in Figure 1 an experienced engineer might reason as follows, even before s/he performs any detailed calculations:

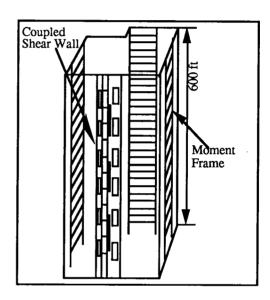


Figure 1: An Example Structure

The height to depth ratio of the structure seems to be quite large and therefore there is a possibility of large overturning moments. The shear walls (in this building) have large openings and hence will behave as frames. This implies that the structure will primarily behave as a frame and therefore is quite flexible. A heuristic rule for obtaining the fundamental period of a structure that acts as a moment frame with a height h is $0.025 * h^{3/4}$. In the present case h is 600 feet. Hence the fundamental period is approximately 3 seconds. Since a frame behaves as a shear beam, the higher modes are likely to correspond to time periods which in the present case - are approximately 1 second, 0.6 seconds, etc. Furthermore since the plan is almost regular, it is sufficient to perform modal

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From: AAAI Technical Report FS-92-01. Copyright © 1992, AAAI (www.aaai.org). All rights reserved. analysis and consider modes of vibration corresponding to 3, 1 and 0.6 seconds to estimate forces and deflections. The overturning moment is likely to be higher than usual since the lateral distribution will be nonlinear instead of being almost linear. The slight non-symmetry in the plan will cause some lateral forces which in turn will cause torsion. Since the shear walls have large openings, there is a possibility of serious degradation of performance due to the torsion. The columns in the first story are very tall and this would cause very large drift in the first floor which might cause non-structural damage. The coupled shear walls are not identical in nature, i.e., they possess different stiffnesses. This can cause large forces in the links and since the links are not restrained laterally, there is a serious possibility of their buckling

The above type of analysis usually occurs during the preliminary design/analysis stage. In the detailed design/analysis stage, the engineer may develop an appropriate numerical model (such as a finite element model), perform the analysis and then interpret the results. All these tasks are knowledge intensive and require considerable engineering judgment.

The above example suggests the following types of knowledge structures and reasoning mechanisms that engineers utilize:

- 1. Objects, such as frame, building.
- 2. Properties that describe the objects, such as height of the building.
- 3. Causality that describes causal relationships between various entities (objects or events), such as non-symmetry causes lateral-forces causes torsion.
- 4. Activities, which consume resources and time, such as the construction of the building.
- 5. Heuristic knowledge, such as:

If the building behaves as a moment frame then the fundamental period of the structure is $0.025 * h^{3/4}$, where h is the height of the structure.

6. Qualitative analysis, such as:

The slight non-symmetry in the plan will cause some lateral forces which in turn will cause torsion.

- 7. Modeling, such as the mapping from the physical world to an engineering model;
- 8. Analogical reasoning, such as:

Since a frame behaves as a shear beam the higher modes are likely to correspond to time periods which are approximately 1 second, 0.6 second, etc.

Here an analogy is made between the frame and the shear beam. Since the higher modes of a shear beam

- are likely to correspond to time periods which are approximately 1 second, 0.6 seconds, etc., the modes of the frame will have similar characteristics.
- 9. Uncertain reasoning, such as the large drift might cause non-structural damage.
- 10. Behavior of Systems, such as the behavior of the shear beam.
- 11. Function, such as the function of a shear wall is to resist lateral loads.
- 12. Spatial Reasoning, such as the reasoning involved in determining that there is non-symmetry in the plan.
- 13. Approximate Quantitative Analysis (back of the envelope calculations), such as:

Calculating stiffness distribution, estimating lateral load distribution etc.

14. Interpretation, such as the interpretation of data from a complex computer analysis.

In addition to the above, engineers deal with time, procedures, design plans, constraints, etc..

In order to effectively address problems such as the one posed above, we need to develop a *comprehensive* knowledge-base (CKB) of engineering knowledge structures. In the next section, we describe a framework that we have been developing for engineering problem solving.

KREEPS: Knowledge Representation Environment for Engineering Problem Solving

KREEPS is being implemented as a layered architecture, as shown in Figure 2. The various layers are briefly discussed below.

- OODBMS. The lowest layer is an object-oriented database management system (OODBMS). Currently we are using EXODUS, which is a C++-based system developed at University of Wisconsin, Madison. The OODBMS is being populated with engineering entities, such as beams, columns, gears, etc, relevant to the civil/mechanical engineering domains
- 2. COSMOS. COSMOS (C++ Object-oriented System Made for expert System development) supports the development of knowledge-based systems. It provides the following extensions to C++:

 1) dynamic schema manipulation; 2) a modified RETE network-based forward chaining strategy; 3) a bayesian-based backward chaining strategy; 3) composite objects; 4) user interfaces for encoding engineering knowledge; etc.
- 3. COPLAN. COPLAN (COnstraint PLANner) is a constraint management system, which uses AI-based planning techniques for solving the constraint satisfaction problem (CSP). A planner is used as a top-level control process, guiding the search for a solution and producing an appropriate solution plan

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by a goal. Usually the goal states which constraints should be satisfied but is more generally a list of assertions that should be true in the final world. The planner produces a non-linear plan at an abstract level where the different steps needed to achieve the goal are partially ordered. At the bottom level, numerical and symbolic methods are chosen in the order defined by the plan. The execution of a plan consists in executing the above procedure. This is very efficient in the case where one wants to vary a parameter over a certain range and to study its influence on other values for a given CSP.

- 4. QRS. QRS is a qualitative reasoner. We are yet to develop this layer.
- 5. GNOMES. One of the basic issues in developing collaborative engineering systems is the representation of the product information which supports sharing. This product information includes not only the geometric data of the physical parts of the product and their relationships but also non-geometric information such as details on functionalities of the parts, constraints, and design intent. We are developing an information model - called SHARED which supports: multiple levels of abstraction and different functional views; multiple levels of geometric representation; and constraint management facilities (COPLAN) for enforcing integrity between various views. The geometric manipulations are performed by GNOMES, which is a non-manifold geometrical modeler. It utilizes the selective geometry complex data structure developed by Rossignac at IBM. GNOMES has been implemented in C++.
- 6. Task Specific Problem Solvers. The kinds of problems that are encountered in engineering can be laid out along a derivation-formation spectrum. In derivation problems, the problem conditions are posed as parts of a solution description; the possible outcomes exist in the knowledge-base. Essentially, the solution to these problems involves the identification of the solution path. In formation (or synthesis) problems, problem conditions are given in the form of properties that a solution must satisfy as a whole. Several domain independent problem solvers addressing various tasks will exist at this level. CONGEN addresses problems at the formation end. It is implemented in C++ and provides extensive support for design problem solving.
- CBR. At this level we will be supporting a casebased reasoner. An architecture for a case-based reasoner has been developed. It is being implemented over COSMOS.
- 8. Knowledge Editing Tools. Adequate user interfaces are provided for encoding various knowledge structures are being developed.

The entire KREEPS framework is being implemented on an $UNIX^{TM}$ workstation, with the user interfaces

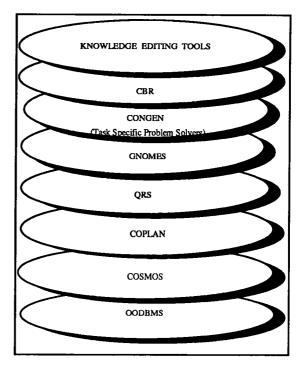


Figure 2: Layered Architecture for KREEPS

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